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Instead, in this work, we study whether directly incorporating multiple alternate reward formulations of the same task in a single agent can lead to faster learning.

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Our method is based on the fact that a deep model can be viewed as a linear prediction layer (i.e., multiple neuron models) and a nonlinear feature extractor (i.e., the network backbone).

On tackling the exploration problem, one general idea that appears in both theory and practice is adding a bonus to the reward to encourage visiting unique states/actions. In theory, a common approach is ...



Single Model and Tang Bonus Methods

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